

Stochastic Submodular Maximization via Polynomial Estimators

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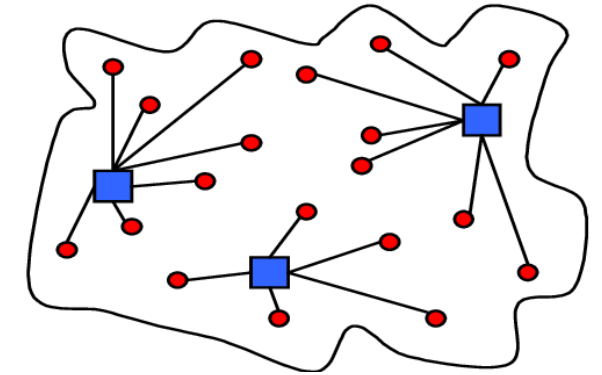
Submodular Function Maximization

- *Submodular function*: set function with diminishing returns

$$\forall A \subseteq B \subseteq V, e \in V$$

$$f(B \cup \{e\}) - f(B) \leq f(A \cup \{e\}) - f(A)$$

- *Examples*: facility location, document summarization, influence maximization, maximum coverage etc.

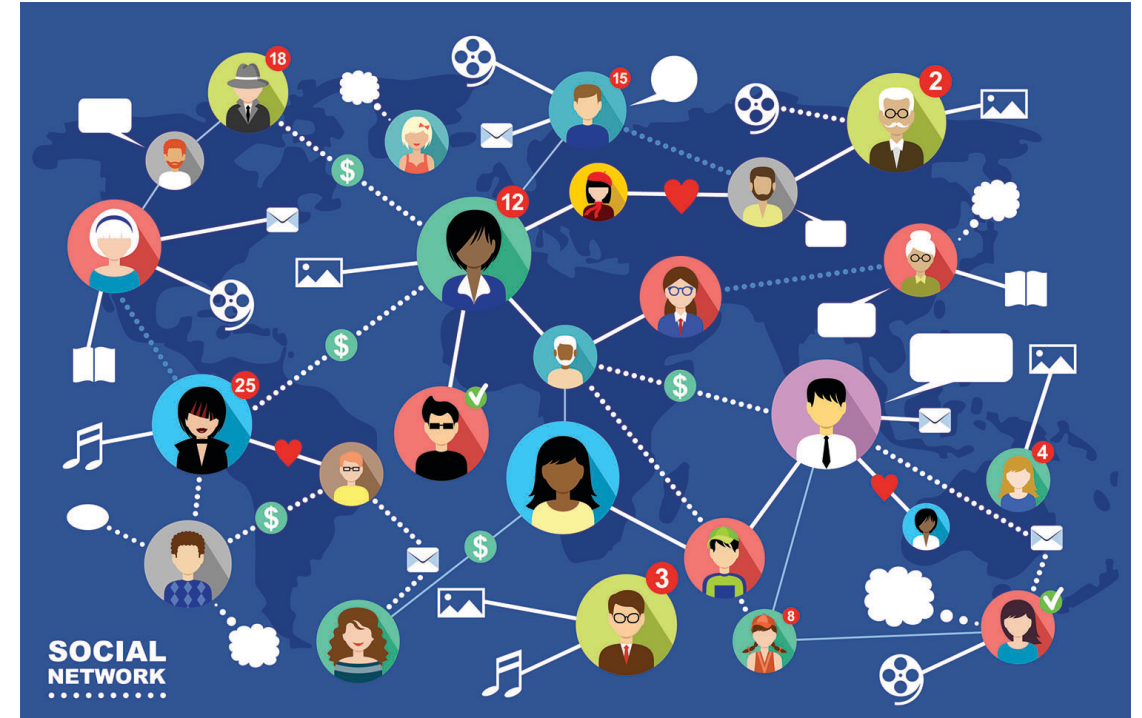


Stochastic Submodular Maximization

- No access to the function oracle

$$f(S) = \mathbb{E}_{z \sim P}[f_z(S)]$$

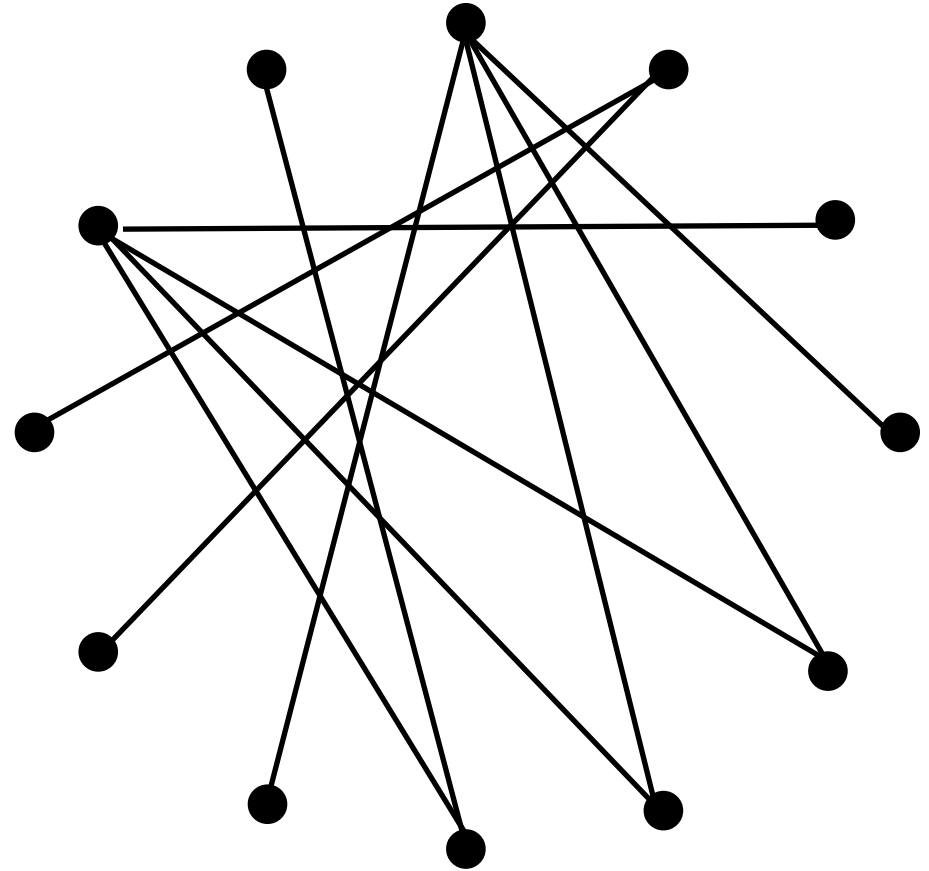
- Only sample a random $f_z(\cdot)$ at a time



Influence Maximization

$$f(S) = \mathbb{E}_{z \sim P} [f_z(S)]$$

- $G = (V, E)$
- Finite set $V = \{1, 2, \dots, n\}$
- Independent Cascades or Linear Threshold [Kempe et al., 2003]
- $f_z(S)$ is the fraction of nodes that are reachable by infecting the seeds $S \subseteq V$



Approximation Algorithms for Stochastic Submodular Maximization



Concave relaxation method achieves $1 - 1/e$ approximation ratio only for coverage functions [Karimi et al., 2017].



Projected gradient methods for general submodular problems achieve $1/2$ approximation ratio [Hassani et al., 2017].



The stochastic continuous greedy algorithm improves this and achieves $1 - 1/e$ approximation ratio on general matroids in poly-time [Mokhtari et al., 2020].

Challenges

- Stochastic Continuous Greedy (SCG) [Mokhtari et al., 2020] uses the *multilinear relaxation*

$$G(\mathbf{y}) = \mathbb{E}_{S \sim \mathbf{y}} [f(S)] = \mathbb{E}_{S \sim \mathbf{y}} [\mathbb{E}_{z \sim P} [f_z(S)]]$$

$$P(i \in S) = y_i, \text{ where } y_i \in [0, 1]$$

- Sampling S to compute the multilinear relaxation (computationally expensive)
- Having two sources of randomness leads to high variance

Submodular Maximization via Taylor Series Approximation [Özcan et al., 2021]

- Multilinear relaxation of a polynomial function is still a polynomial function.
- $G(\mathbf{y})$ is computed efficiently if f is well approximated by a polynomial.

$$\underbrace{\mathbb{E}_{\mathbf{x} \sim \mathbf{y}} [p(\mathbf{x})]}_{\text{does not require sampling!}} = \mathbb{E}_{\mathbf{x} \sim \mathbf{y}} [\dot{p}(\mathbf{x})] = \dot{p}(\mathbf{y})$$

polynomial polynomial

$$i \in S \iff x_i = 1$$
$$i \notin S \iff x_i = 0$$

Our Contributions

- We extend the notion of polynomial estimators of multilinear relaxations [Özcan et al., 2021] to stochastic submodular optimization
 - No sampling
 - One source of randomness
- Theoretical guarantees
 - Bias/variance trade off

Outline

- Stochastic Setting
- Polynomial Estimator & Main Theorem
- Conclusion & Future Work

Stochastic Setting

- Discrete stochastic submodular maximization
- Set function $f: 2^V \rightarrow \mathbb{R}_+$ of the form:

$$f(S) = \mathbb{E}_{z \sim P}[f_z(S)]$$

where $S \subseteq V$, where z is the realization of the random variable Z is drawn from a distribution P .

- For each realization of $z \sim P$, $f_z: 2^V \rightarrow \mathbb{R}_+$ is monotone and submodular.
- Objective is:

$$\max_{S \in \mathcal{I}} f(S) = \max_{S \in \mathcal{I}} \mathbb{E}_{z \sim P}[f_z(S)],$$

where \mathcal{I} is a general matroid constraint.

Binary Notation

- Binary vector \mathbf{x} whose support is S :

$$S \subset V \iff \mathbf{x} \in \{0, 1\}^N$$

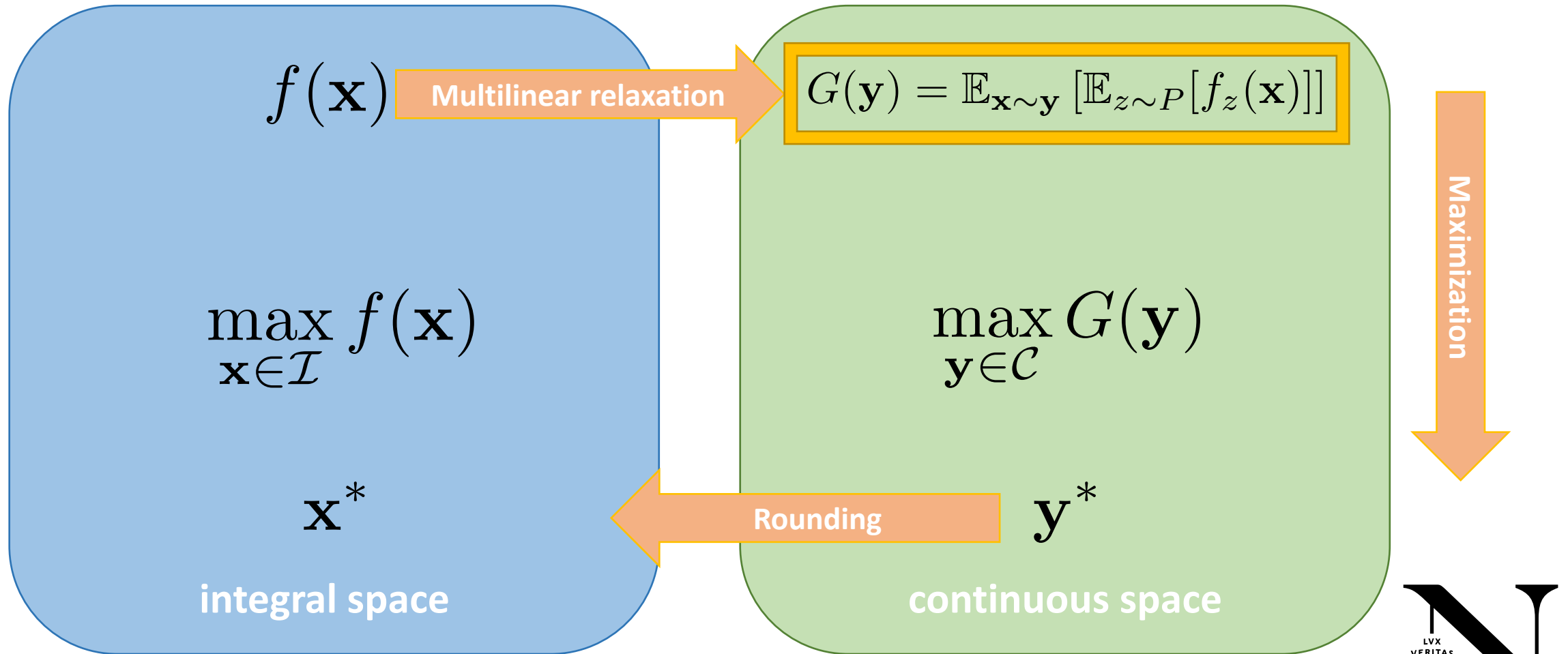
$$i \in S \iff x_i = 1$$

$$i \notin S \iff x_i = 0$$

$$\boxed{\max_{S \in \mathcal{I}} f(S)} \iff \boxed{\max_{\mathbf{x} \in \mathcal{I}} f(\mathbf{x})}$$

Stochastic Continuous Greedy Algorithm

[Mokhtari et al., 2020]



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Assumptions

- 1) Function $f: \{0, 1\}^N \rightarrow \mathbb{R}_+$: $f(S) = \mathbb{E}_{Z \sim P}[f_Z(S)]$ is monotone and submodular.
- 2) Elements in the constraint set \mathcal{C} are uniformly bounded, i.e.,
$$\|y\| \leq D.$$
- 3) For all $x \in \{0, 1\}^n$, there exists $\varepsilon_z(L) \geq 0$ such that $\lim_{L \rightarrow \infty} \varepsilon_z(L) = 0$ and

$$|f_z(\mathbf{x}) - \hat{f}_z^L(\mathbf{x})| \leq \underbrace{\varepsilon_z(L)}_{\text{bias}}.$$

bias

$\hat{f}_z^L(\cdot)$: polynomial estimator of $f_z(\cdot)$

L : degree of the polynomial

Variance of the Gradients

- Variance of the unbiased gradients [Mokhtari et al., 2020]:

$$\sigma^2 = \sup_{\mathbf{y} \in \mathcal{C}} \mathbb{E} \left[\|\widehat{\nabla G_z(\mathbf{y})} - G(\mathbf{y})\|^2 \right]$$

- Variance of the biased gradients:

$$\sigma_0^2 = \sup_{\mathbf{y} \in \mathcal{C}} \mathbb{E}_{z \sim P} \left[\|\nabla G_z(\mathbf{y}) - \nabla G(\mathbf{y})\|^2 \right]$$

- Mean bias:

$$\varepsilon(L) = \mathbb{E}_{z \sim P} [\varepsilon_z(L)]$$

Main Theorem

- Assume a function $f: \{0, 1\}^N \rightarrow \mathbb{R}_+$ satisfies these assumptions. Then, consider the stochastic continuous greedy algorithm in which $G(\mathbf{y})$ is estimated via the sample or the polynomial estimator. Then,

$$\mathbb{E}[G(\mathbf{y}_T)] \geq (1 - 1/e)OPT - \frac{15DK}{T^{1/3}} - \frac{f_{\max}rD^2}{2T}$$

Unbiased version: $K \approx 4\sigma + \sqrt{3r}f_{\max}D$

Biased version: $K \approx \sqrt{16\sigma_0^2 + 224\sqrt{n}\varepsilon(L)} + 2\sqrt{r}f_{\max}D$

Examples

	Input	$g_z : \{0, 1\}^{ V } \rightarrow [0, 1]$ $\mathbf{x} \rightarrow g_z(\mathbf{x})$	$f_z : \{0, 1\}^{ V } \rightarrow \mathbb{R}_+$ $\mathbf{x} \rightarrow f_z(\mathbf{x})$	$\hat{f}_z^L : \{0, 1\}^{ V } \rightarrow \mathbb{R}_+$ $\mathbf{x} \rightarrow \hat{f}_z^L(\mathbf{x})$	Bias $\varepsilon(L)$
SM	Weighted bipartite graph $G = (V \cup P)$ weights $\mathbf{r}_z \in \mathbb{R}_+^n$, and $\sum_{i=1}^n r_{i,z} = 1$	$\sum_{i \in V \cap P_j} r_{i,z} x_i$	$\sum_{j=1}^J h(g_z(\mathbf{x}))$, where $h(s) = \log(1 + s)$	$\hat{h}^L(g_z(\mathbf{x}))$	$\frac{1}{(L+1)2^{L+1}}$
IM	Instances $G = (V, E)$ of a directed graph, partitions $P_v^z \subset V$	$\sum_{i \in V} \frac{1}{N} \left(1 - \prod_{u \in P_i^z} (1 - x_u) \right)$	$h(g_z(\mathbf{x}))$ where $h(s) = \log(1 + s)$	$\hat{h}^L(g_z(\mathbf{x}))$	$\frac{1}{(L+1)2^{L+1}}$
FL	Complete weighted bipartite graph $G = (V \cup V')$ weights $w_{i_\ell, z} \in [0, 1]^{N \times z }$	$\sum_{\ell=1}^N (w_{i_\ell, z} - w_{i_{\ell+1}, z}) \left(1 - \prod_{k=1}^{\ell} (1 - x_{i_k}) \right)$	$h(g_z(\mathbf{x}))$ where $h(s) = \log(1 + s)$	$\hat{h}^L(g_z(\mathbf{x}))$	$\frac{1}{(L+1)2^{L+1}}$
CN	Graph $G = (V, E)$, service rates $\mu \in \mathbb{R}_+^{ z }$, requests $r \in \mathcal{R}$, P_z path of r , arrival rates $\lambda \in \mathbb{R}_+^{ \mathcal{R} }$	$\frac{1}{\mu_z} \sum_{r \in \mathcal{R}: z \in p^r} \lambda^r \prod_{k'=1}^{k_p^r(v)} (1 - x_{p_k^r, i^r})$	$h(g_z(\mathbf{0})) - h(g_z(\mathbf{x}))$ where $h(s) = s/(1 - s)$	$\hat{h}^L(g_z(\mathbf{x}))$	$\frac{\bar{s}^{L+1}}{1 - \bar{s}}$

$$\lim_{L \rightarrow \infty} \varepsilon(L) \rightarrow 0$$



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Conclusion & Future Work

- We propose an alternative to the sampling estimator
 - polynomial,
 - achieves $1 - 1/e$ approximation ratio,
 - with only one source of randomness.
- A similar extension can be made to the online setting with regret analysis.



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Thank you!



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